Running time Analysis of Sorting Algorithm via an Asymptotic Distribution

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Abstract:- Sorting data is one of the most important problems that play an important rule in many applications in operations research and computer science. Many sorting algorithms are well studied but the problem is not to find a way or algorithm to sort elements, but to find an efficiently way to sort elements. The output is a stream of data in time. We are interested in this flow of data. For the performance of such algorithms, there has been little research on their stochastic behavior and mathematical properties. In this paper we study the mathematical behavior of some different versions sorting algorithms. We also discuss the corresponding running time using some different strategies.

Keywords: five key Sorting, Algorithms, divide and conquer, Performance, stochastic process, Convergence cadlag functions, asymptotics, Skorodhod metric.

I. INTRODUCTION

Classical analyses of sorting algorithms make the efficiency is the general purpose. The efficiency of the good algorithm depends on many various factors such as, software and hardware use. More recently researchers have recognized that on modern computers the cost of accessing memory can vary dramatically depending on whether the data can be found in the first-level cache, or must be fetched from a lower level of cache or even main memory. The efficiency of an algorithm using a poor code, is differ than using a good code, in addition the operating system itself. The running time of executing sub-arrays is particularly important for sorting because the inner-loops of most common sorting algorithms consist of comparisons of items to be sorted. Thus, the expected of these comparisons to do the job is critical to the performance of sorting algorithms. Throughout this paper we ignore all aspects of these factors unless the the behavior the sorting scheme whose outcome depends on a number of comparisons needed to the sorting algorithm in its input.

Selecting a good pivot is important. A poor choice of a pivot could give a running time quadratic proportional to the number of elements squared. Therefore selecting a good pivot greatly improves the speed of the Quicksort algorithm. Many people just use the first element in the list as the pivot, however this causes the sort to perform very badly if the data is already sorted. There are several methods to avoid the worst case in practical solutions. Unix uses the median of the first the last and the element in the middle. Therefore, when choosing the pivot we need to be more careful. For example, when Quicksort is used in web services, it is possible for an attacker to intentionally exploit the worst case performance and choose data which will cause a slow running time or maximize the chance of running out of stack space. The choice of a good pivot greatly improves the speed of the Quicksort algorithm.

The simplest way is to choose an arbitrary element say the first for example as pivot, this does not avoid the worst case. Instead of using the first element, a much better method is called median of three Quicksort. In that method choose the pivot of each recursive stage as the median of a sample of three elements. Other method is to take tree samples, each sample contain 3 elements, take the median for each sample and choose the median of three medians as a pivot, this method called pseudomedian of 9 Quicksort.

To make sure to avoid any kind of presorting it is better to use the median element of the first, middle, and the last element as a pivot. To optimize the algorithm, for an array smaller than 7, the pivot is chosen as the middle key or sort with the standard Quicksort, for mid-sized arrays (for an array of size between 8 and 39) the pivot is chosen using the median-of-three Quicksort, and finally for larger arrays use the pseudomedian of 9 Quicksort. This helps some but unfortunately small anomalies happens [1].

Some recent papers considered a version of Quicksort algorithm called the random median Quicksort. For a random variable k, the pivot element has been selected to be the median of 2k+1 elements. In each step recursively recall of the algorithm. Later, many researchers has received the interest of the visualization of multi-pivot Quicksort in accordance with Yaroslavskiy proposed the duality pivot process which outperforms standard Quicksort by Java JVM. After that, this algorithm has been explained in terms of comparisons and
Swaps by Wild and Nebel [6]. Not long ago, a new version from Dual-pivot Quicksort algorithm has some other number \( k \) of pivots. Hence, we discuss the idea of picking \( k \) pivots, \( k = 1,2, \ldots, n \) by random way and splitting the list simultaneously according to these. The modified version generalizes these results for multi process. We show that the average number of swaps done by Multi-pivot Quicksort process and a special case. Moreover, [7] obtained a relationship between the average number of swaps of Multi-pivot Quicksort and Stirling numbers of the first kind.

Let \( X_n \) be the number of comparisons used by Quicksort to sort a list of size \( n \). The random variable \( X_n \) is basically proportional to the running time of Quicksort which depends (a little bit) on the implementation and computer hardware. The average number \( E(X_n) \) of comparisons [1] is \( E(X_n) \approx n \ln n \). The first complete running time analysis for a random divide and conquer was for Quicksort [13]. The random variable

\[
Y_n = \frac{X_n - E(X_n)}{n}
\]

converges in distribution to a random variable \( Y \), which distribution is characterized as the unique solution of the stochastic fixed point equation

\[
Y \overset{D}{=} U Y^1 + (1 - U) Y^2 + C(U)
\]

with expectation 0 and finite variance. Here \( U \) is uniformly distributed on \([0,1]\) and \( U, Y^1, Y^2 \) are independent. \( Y^1 \) and \( Y^2 \) have the same distribution and \( C \) is given by

\[
C(x) := 2x \ln x + 2(1-x) \ln(1-x) + 1, \quad x \in [0,1].
\]

Quickselect or FIND, introduced by Hoare [2] in 1961 is a search algorithm widely used for finding the \( l \)-th smallest element out of \( n \) distinct numbers. Most of the mathematical results on the complexity of Quickselect are about expectations or distributions for the number of comparisons needed to complete its task by the algorithm [10]. A pivot is uniformly chosen at random from the available \( n \) elements, and compares the \( n-1 \) remaining elements against it.

Let \( X_n(k) \) be the number of comparisons needed to find the \( l \)-th smallest out of \( n \) elements. The running time of this algorithm is always a random variable either by random input or internal randomness. The expectation of \( X_n(k) \) is explicitly known [1]

\[
E(X_n(k)) = 2(n+3+(n+1)H_n - (k+2)H_k - (n+3-k)H_{n+1-k})
\]

for \( 1 \leq k \leq n \), and \( H_k \) denotes the \( k \)-th harmonic number. An asymptotic approximation as \( n \to \infty \) is

\[
\frac{E(X_n(k))}{n} \approx 2 - 2l \ln n - 2(1-t) \ln(1-t)
\]

for \( 0 \leq t = \frac{kn}{n} \leq 1 \). The asymptotic variance \( Var(X_n(k)) \) was derived using combinatorial and generating function methods [10]. Furthermore, Roesler [9] studied the limiting distribution of \( X_n(k) \) or \( X_n \) as a process. A major tool are fixed point equation and the contraction method for operator \( K \) like

\[
K(\mu) = \sum_{i \in N} A_i Y_i + C
\]

The random variables \((A,B,C), Y_i, i \in N\) are independent and the random variables \( Y_i \) have the same distribution \( \mu \). In a more general form of (1), Knof and Roesler [3] considered general recurrence

\[
Y^n = \sum_{i \in N} A^n Y_i \circ B^n_i + C^n
\]

on the set \( D \) of cadlag functions on the unit interval \([0,1]\). Here \((A^n_i,B^n_i, l^n_i), C^n), Y_i, i,j,k \in N\) are all independent. \( Y_i, A^n_i, C^n \) have values in the set \( D \). The random variables \( B^n_i \) take values in \( D \), the set of all maps from the unit interval to itself and piecewise increasing.

Under some assumptions they showed the existence of solutions of (2) via the weighted branching process, and \( Y^n \) converges in distribution to \( Y \) satisfying

\[
Y = \sum_{i \in N} A Y_i \circ B_i + C
\]
The contraction method invented for the analysis of Quicksort, proved to be very successful for other algorithms [5, 11]. The contraction method is a general method to derive convergence in distribution of recursive structures. This method was pioneered by Roesler [11] and later by Neininger [5]. This method was explained in the context of several divide and conquer algorithms in [11]. Knof [3] studied the finite dimensional distributions of D-valued processes $Y^n$ by the contraction method. He introduced a suitable complete metric space and showed convergence of all finite dimensional distributions. His results include Quicksort. A nice version of the Quickselect processes is used to and show the convergence in other topology to a limiting process $Y$ which is a fixed point of the map $K$ [8]. In our work, we use a smart approach to show the existence of partial sorting process via the weighted branching process. Our approach was inspired by the methods used for the analysis of Quickselect [8], where fixed point equations on $D$ were considered for the first time.

The equation (2) implies the distributional equality and $Y = Y^\otimes$ satisfies the fixed point equation (12). The family $Y^l$ is explicitly given in [8]. Also consider [9] for further details.

This result is a probabilistic result and we obtain it via the Weighted Branching Process [12] and an explicitly given nice family of processes $Y_n^l$ indexed by $n \in \mathbb{N}$ and the binary tree. Basically we use the splitting $U$ - rvs for the $Y$ process also for the $Y_n$ process.

II. THE RECURSIVE EQUATION OF COMPARISONS

Like in the classical Quicksort [2], choose with a uniform distribution a pivot, split the set $S$ of numbers into the set $S_\prec$ of strictly smaller ones than the pivot, the pivot and the set $S_\succ$ of strictly larger ones in this order. Then continue recalling Quicksort always for the left list $S_\prec$. If $S_\prec$ is empty continue with the next leftmost sublist recalling the algorithm. If $S_\prec$ consists only of one element, output this number immediately and continue with the next leftmost list. Now define the random variable, $X(S,l)$ of comparisons required to sort $l$ smallest elements in an array of distinct $|S|$ numbers. The random variable $X$ satisfies the recursive formula

$$X(S,l) = \lfloor |S| \rfloor - 1 + \sum_{i=1}^{l} X^{i}(S_\prec, l) + \sum_{i=1}^{l} \left( X^{i}(S_\prec, l-1) + X^2(S_\succ, l-I) \right)$$

for $l = 1, 2, \ldots, |S|$.

Here $I = I(S) = |S_\prec | + 1$ denotes the rank of the pivot after comparisons. $I$ means the index of the position it occupies in the sorted sequence and has values in $\{1, 2, \ldots, n\}$ with a uniform distribution. The rv $I$ is independent of all $X$ random variables in equation (17). The random variable $X(S_\prec, l)$ satisfies a similar recursion, where $I(S_\prec, l)$ is independent of everything before. Continuing this way we find the distribution of $X(S,l)$ as the Quicksort distribution sorting $S$ by standard Quicksort. In the next proposition we will show that the distribution of $X(S,l)$ depends on $S$ only via the size $n$ of $S$

**Proposition 2.1** Let $S, \widetilde{S}$ be two sets of $n$ different reals, and let $l = 1, 2, \ldots, n$. Then

$$L(X(S,l)) = L(X(\widetilde{S}, l)).$$

Proof.

By induction on $n$. It is true for $n = 1$ and we are done. Assume it is true for $k \leq n$, so we use the notation

$$L(X(S,l)) = L((X(S,l))_i) \text{ for } |S| \leq k. (5)$$

The random variable $I(S) = I(|S|)$ is uniformly distributed on $\{1, 2, \ldots, n\}$. Let $(X^1(k,l))_{k \in \{1, 2, \ldots, k\}}$, $(X^2(k,l))_{k \in \{1, 2, \ldots, k\}}$ be independent random variables independent of $I$ and with the distribution given in (5). Since $|S_\prec |, |S_\succ | \leq n$, then

$$L(X^1(S_\prec, l)) = L((X(\widetilde{S}, l))_i) \text{ and } L(X^1(S_\succ, l)) = L((X(\widetilde{S}, l))_i).$$

Now let $|S'| = |\widetilde{S}'| = n + 1$. Then

$$L(X(S,l)) = \sum_{i=1}^{n+1} P(I = i) L(k-1 + \sum_{i=1}^{l} X^1(S_\prec, l) + \sum_{i=1}^{l} (X^1(S_\prec, l-1) + X^2(S_\succ, l-i))).$$
\[
\sum_{i=1}^{k+1} P(I = i) L((k-1+1_{|S|} X_1^1(i-1,I) + 1_{n}X_1^1(i-1,I-1) + X^2(n-i,l-I))_{I})
= \sum_{i=1}^{k+1} P(I = i) L((k-1+1_{|S|} X_1^1(S_1^1,l-I) + 1_{n}X_1^1(S_1^1,l-I) + X^2(S_1^1,l-I))_{I})
= L(X(S,I))_{I}.
\]

Then \( L(X(S,I)) = L(X(k+1,I)) \). Then the statement is true for \( n = k+1 \) and therefore true for all \( n \in \mathbb{N} \).

**Remark:**
The above Proposition is true states that the distribution of \( X(S,I) \) depends only on \( |S| \) and \( l \). The equation (17) determines the distribution of \( X(S,I) \) via the distribution for smaller sets and notice \( I(S) = I(|S|) \)

\[
X(n) = \sum_{l=0}^{n} X(l,|S|)+1_{n}X(l-1,|S|)+1_{n}X(l-1,|S|)+1_{n}X(l-1,|S|)+ \ldots + X^2(n-1,|S|)+1_{n}X^2(n-1,|S|)+ \ldots + X^2(n-1,|S|)+1_{n}X^2(n-1,|S|)
\]

For the distribution of \( X(n) = (X(n,l))_{l=1,2,\ldots,n} \). We consider \( I_n \), \( (X(i,j))_{i=1,2,\ldots,n} \) are independent. The rv \( I_n \) has values on \( \{1,2,\ldots,n\} \). \( X^2(j,i) \) has the same distribution as \( X(j,i) \) by recursion. We put for notational reasons (boundary conditions) \( X(j,i) = 0 = X^2(0,0) \) for \( i = 1,2 \). Notice \( X(n,n) = X(n,n-1) \).

In our version of Quicksort we use internal randomness by picking the pivot by random with a uniform distribution. Like in standard Quicksort, we could instead of internal randomness also use external randomness. Choose as input a uniform distribution on all permutations \( \pi \) of order \( n \) and pick as pivot any, for example always the first in the list. Now \( X(n) \) is a deterministic function depending on the input \( \pi \). As a rv with random input \( \pi \) we face the same distribution as with internal randomness. The main advantage using internal randomness is the same distribution of \( X \) for every input of the same size. Alternatively we could start with iid random variables uniformly on \([0,1] \) and choose as pivot always the first element of the list. The algorithm itself would be deterministic, the time spend \( (= X) \) is a rv via the input of an iid sequence.

From equation (6) we obtain a recursion for the expectation \( a(n,l) = E(X(n,l)) \)

\[
a(n,l) = n - 1 + \sum_{j=0}^{n} a(j,l+j) + a(n-j,l-j) + \sum_{j=0}^{n} a(j-1,l)
\]

The term \( a(n,n) \) is the expectation of sorting \( n \) numbers by Quicksort. All \( a(n,l) \) are uniquely defined by the above equations and the starting conditions. Martinéz [4] obtained the explicit formula

\[
a(n,l) = 2n + 2(n+1)H_n - 2(n+3-l)H_{n+1-l} - 6l + 6 \quad (7)
\]

\( 1 \leq l \leq n \in \mathbb{N} \). (Notice not for \( n = 0 \) and \( l = 0 \).) \( H_j \) denotes the \( j \)-th harmonic number \( H_j = \sum_{i=1}^{j} \frac{1}{i} \). For Quicksort we obtain the well known formula \( a(n,n) = 2(n+1)H_n - 4n \).

Martinéz argued with Partial Quicksort \( PQ(n,l) \), which for fixed \( n,l \) sorts the \( l \) smallest elements of a list. For more results and versions of it, optimality and one-dimensional distributions for Partial Quicksort see [4]. The Quicksort process is an extension of Partial Quicksort in the sense of taking \( l \) as a time variable. We find first the \( l-1 \)-smallest elements, then continue this search for the \( l \)-th smallest, then \( l+1 \)-th smallest and so on. Now to the distribution of the process \( X(n,i) \) in the limit. This is the question, how much \( X(n,l) \) differs from the average \( a(n,l) \). We suggest a normalization of \( X(n,l) \) to obtain a non degenerate limit distribution. Often this is the random variables of the form

\[
Y_n(l,1) = \frac{X(n,l) - a(n,l)}{n}
\]

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for \( l = 1, \ldots, n \) and \( Y_n(1) = Y_n\left(\frac{n-1}{n}\right) \) satisfy the recursion, \( n \geq 1 \)

\[
\left( Y_n\left(\frac{l}{n}\right) \right)_{0 \leq l \leq n} = \left( C(n, l, l_n) + 1_{l \leq l_n} \frac{n-1}{n} Y_{l_n-1}^1 \left( \frac{l}{l_n-1} \right) + 1_{l > l_n} \left( \frac{n-1}{n} Y_{l_n-1}^1 (1) + \left( 1 - \frac{1}{n} \right) Y_n^2 \left( \frac{l-l_n}{1-l_n} \right) \right) \right)_{0 \leq l \leq n}
\]

\[
C(n, l, i) = \frac{1}{n} (n-1) 1_{l \leq i} (a(i-1, i+1) + \sum_{i=1}^{n} (a(i-1, i+1) + a(n-i, l+1-i))
\]

Notice \( Y_n \) is well defined and there are no boundary conditions besides \( Y_0 = 0 = Y_1 \).

We extend the process \( Y_n \) nicely to a process on the unit interval \([0,1]\) with values in the space \( D = D[0,1] \) of c.d.f. (right continuous functions with existing left limits) on the unit interval. This can be done by linear interpolation or a piece wise constant function. We shall use the extension

\[
Y_n(t) := Y_n\left(\frac{\lfloor nt \rfloor}{n}\right)
\]  

for \( n \in \mathbb{N} \). In short notation

\[
Y_n = \varphi_n(U_n, Y_1^1)_{k \leq n \leq \infty}, \varphi_n(Y_2^2)_{k \leq n}
\]  

for a suitable function \( \varphi_n \).

If \( n \to \infty \) then \( U_n \) converges in distribution to a rv \( U \) with a uniform distribution. We might expect that the process \( Y_n \) converges in some sense to a limiting process \( Y = (Y(t))_{t \geq 0, [0,1]} \) with values in \( D \) satisfying something like the stochastic fixed point equation

\[
Y = \left( Y_1 U + 1_{U \leq \frac{1}{2}} (UY)^1 (1) + U Y^2 \left( \frac{1-U}{1-U} \right) + C(U, t) \right)_{t \geq 0}
\]

for a suitable function \( \varphi \). The rvs \( Y^1, Y^2, U \) are independent. \( Y^1 \) and \( Y^2 \) have the same distribution as \( Y \) and \( U \) is uniformly distributed on the unit interval \([0,1]\). The cost function \( C = C(U, \cdot) \) is given by

\[
C(u, t) = C(u) + 2 \int_0^u ((1-t) \ln(1-t) - (1-u) \ln(1-u) - (u-t) \ln(u-t) - (1-u))
\]

and is the limit of \( C(n, l, i) \) with \( \frac{1}{n} \to n, \frac{i}{n} \to n \). [8].

### III. BINARY ULAM-HARRIS TREES

To ensure a high Consider the infinite Ulam-Harris tree

\[
V := \bigcup_{n \in \mathbb{N}^\mathbb{N}} \mathbb{N}^n
\]

be the infinite tree rooted at \( \{ \phi \} \) where \( \mathbb{N} = \{ 1,2, \ldots \} \) denotes the set of positive integers and by convention \( \mathbb{N}^0 = \{ \phi \} \) contains the null sequence \( \phi \). Each \( v = (v_1, v_2, \ldots, v_n) \in \zeta \) is called a node or vertex which we also write as \( v_1 v_2 \ldots v_n \). The vertex \( v \) is uniquely connected to the root \( \phi \) by the path \( \phi \to v_1 \to v_1 v_2 \to \ldots \to v_1 \ldots v_n \).

The length of \( v \) is denoted by \( |v| \), thus \( |v_1 \cdots v_n| = n \) and in particularly we use \( |\phi| = 0 \). For all \( v \in \zeta \) and for every \( k \in \mathbb{N} \) define

\[
\nu_k := \begin{cases} \phi & k = 0 \\ v_k & k < |v| \\ v & k \geq |v| \end{cases}
\]

Further we use the notations for \( w = w_1 \ldots w_m \), \( w^w := v_1 v_2 \ldots v_n w_1 w_2 \ldots w_m \), and \( \nu : = v \) and \( \nu \phi : = v \).
In our work we suppress if possible the root $\phi$.

**Definition 3.1** For all $v, w \in \zeta$, the prefix order $\prec$ on $\zeta$ is given by $v^\prec w \iff \exists u \in \zeta : uv = w$.

The node $v$ is called an ancestor or progenitor of $w$ and conversely $w$ is called a descendant of $v$. If $u \in \mathbb{N}$, then $v$ is also called a mother of $w$ and, conversely, $w$ is called a child or offspring of $v$.

We further define $v \prec w \iff v^\prec w \land v \neq w$.

In the context of branching tree, the relation $v \prec w$ may be interpreted as, the node $v$ is strictly older than $w$ in terms of generations. We extend this definition to subsets of $\zeta$. For all $L \subseteq \zeta$ and $v \in \zeta$, define $v^\prec L \iff \exists w \in L : vw \in L$ and $L \prec v \iff \exists w \in L : w \prec v$.

We use the $m$-ary tree $\{1, \ldots, m\}^*$, the tree is called binary tree. Let $(\Omega, \Lambda, P)$ be a probability space, rich enough to carry all occurring random variables in our work. Let $(G, \ast)$ be a measurable semigroup (\* : $G \times G \rightarrow G$, $(g, h) = g \ast h$ associative and measurable) with a grave $\Delta$ (\(\forall g \in \Delta : \Delta \ast g = \Delta = g \ast \Delta\)) and a neutral element $e$ (\(\forall g \in G : e \ast g = g = g \ast e\)).

The semigroup $(G, \ast)$ operates transitive and measurable on the measurable space $H$ via $\otimes : G \times H \rightarrow H$ and $G \times H$ is endowed with the product $\sigma$-field. Let $T : \Omega \rightarrow C^N$ be a random variable relative to the product space.

We use the notation $T = (T_1, T_2, \cdots)$, where $T_i : \Omega \rightarrow G$ is the $i$-th projection of $T$. Let $C : \Omega \rightarrow H$ be a random variable with values in a measurable semigroup $H$.

Let $(T^v, C^v), v \in \mathcal{V}$, be independent copies of $(T, C)$ on the same probability space $(\Omega, \Lambda, P)$. We call $T_i^v$, the weight attached to the edge $(v, vi)$ connecting $v$ and $vi$. $C^v$ is called the weight of the vertex $v$. The interpretation of $C^v$ is as a cost function on a vertex $v \in \zeta$. A tuple $(\mathcal{V}, (T, C), (G, \ast), (H, \otimes))$ as above is called a weighted branching process (WBP). For a weighted branching process without costs we write also $(\mathcal{V}, (T, (G, \ast)))$. We shall use freely other trees such as $m$-ary tree $\{1, 2, \cdots, m\}^*$ of all sequences in an appropriate sense. The interpretation of $G$ is as maps from $H$ to $H$. If $H$ has additional structure then we might enlarge $G$ to have the induced structure.

For example if $H$ is a vector space or an ordered set, we may extended $G$ to a vector space of maps or ordered sets via the natural extension.

**Definition 3.2** Define recursively a family $L := (L_v)_{v \in \zeta}$ of random variables $L_v : \Omega \rightarrow G$ by

$L_\phi := e$, $L_{vi} := L_v \ast T_i^v$ for all $v \in \mathcal{V}, i \in \mathbb{N}$.

We call $L_v$ the path weight from the root $\phi$ to the node $v$. Similarly, we define recursively for all $v \in \zeta$, the family of path weights from $v$ to $vw$ $L^w := (L^w_v)_{v \in \zeta}$ by

$L^w_\phi := e$, $L^w_{wi} := L^w_v \ast T_i^{vw}$ for all $w \in \zeta, i \in \mathbb{N}$. \hspace{1cm} (14)

The path weight $L_v$ has the following product representation

$L_v = T_1^v \ast T_2^{v1} \ast T_3^{v12} \ast \cdots \ast T_n^{v12\cdots n-1} = \prod_{k=1}^{n-1} T_{k+1}^{v_k}$ \hspace{1cm} (15)

for $v = v_1v_2 \cdots v_n$. Hence $L_v$ is just the accumulated multiplicative weight along the path connecting the root $\phi$ with the node $v$. $L_v$ forms the total weight of the branch starting from the root $\phi$ to node $v$ accumulated under operation $\ast$ of the edge weights.

An individual or a node $v$ is called alive, if $L_v = \Delta$, otherwise the node is called dead. In particular all nodes with weight $\Delta$ are skipped in pictures. Define the total weight (cost) regarded up to the $n$-th generation by

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\[ R_n := \sum_{|t|=n} L_v \otimes C^v, \quad n \in \mathbb{N} \]  \hspace{1cm} (16)

Because we deal only with positive values, everything will be well defined in our examples. We explain the forward and backward view via a weighted branching process on \( P^+ \) for simplicity. The same argument will hold later for the weighted branching process \((\xi, (T, C), (D^*, (D^*_n, \otimes)))\). Consider a weighted branching process \((\xi, (T, C), (P^+), (P, .))\).

For the next sections we need the following two examples. Although they provide known results the novelty is the line of arguments, which can be generalized and which are the key for the Quicksort process.

**Example 3.1** Here we show mainly the existence of the Quicksort distribution. Consider the weighted branching process \(([1,2]^*, (P, .), (U, 1-U, C(U)))\) with \( U \) has a uniform distribution and
\[ C(x) := 1 + 2x \ln x + 2(1-x) \ln(1-x). \]  \hspace{1cm} (17)
\( G \) is the multiplicative semi group \( P \) with the neutral element \( e = 1 \) and the grave \( \Delta = 0 \). \( G \) operates transitive on \( H = P \) by multiplication. Let \( U^v, v \in V \) be independent rvs with a uniform distribution on \([0,1]\).

Put \( T_1^v = U^v, \ T_2^v = 1-U^v, \ C^v = C(U^v) \).

Since \( H \) is an ordered vector space, we extend \( G \) with the interpretation of maps to the ordered vector space generated by the maps. The total weighted cost \( R_m := \sum_{v \in V_{cm}} L_v C^v \) up to the \( m-1 \) generation is an \( L_2 \)-martingale and converges in \( L_2 \) and a.e. to a rv \( Q \). The distribution of \( Q \) is called the Quicksort distribution.

The distribution is uniquely characterized [10] as the solution of the stochastic fixed point equation
\[ N \stackrel{D}{=} UQ_1 + (1-U)Q_2 + C(U) \]  \hspace{1cm} (18)
with expectation 0 and finite variance. Here \( = \) denotes equality in distribution. The random variables \( U, Q_1, Q_2 \) are independent, \( U \) is uniformly distributed and \( Q_1, Q_2 \) have the same distribution as \( Q \).

By the a.s. convergence of \( R_m = \sum_{v \in V_{cm}} L_v C^v \) the rvs
\[ Q^v := \sum_{v \in V} L_v C^v \]  \hspace{1cm} (19)
exist and satisfy a.e.
\[ Q^v = U^v Q^{v1} + (1-U^v)Q^{v2} + C(U^v) \]  \hspace{1cm} (20)
for every \( v \in V \). Of course the distribution of \( Q^v \) is a solution of (18).

**Example 3.2** Convergence of the discrete Quicksort distributions [9]. The original problem concerns the number \( X_n \) of comparisons to sort \( n \) distinct reals. We use internal randomness. Then for \( n \in \mathbb{N} \)
\[ X_n = n - 1 + X_1^{i-1} + X_2^{i-1} \]
with \( I_n, X_1^{i}, X_2^{i} \) are independent, \( I_n \) has a uniform distribution on \( 1, \ldots, n \) and \( X_1^{i}, X_2^{i} \) have the same distribution as \( X_i \). The boundary conditions are \( X_0 \) and \( X_1 \) are identical 0. The expectation of \( X_n \) is \( a_n = a(n, n) \). The normalized rvs \( Y_n = \frac{X_n - a_n}{n} \) satisfy the recursion
\[ Y_n = \frac{D}{n} I_{n-1}^{i-1} Y_{n-1}^{i-1} + \frac{n-I_n}{n} Y_{n-1}^{i} + C_n(I_n) \]
where
\[ C_n(i) := \frac{n - 1 - a_n + a_{i-1} + a_{n-i}}{n} \]
Now the abstract embedding into a WBP with an additional parameter \( n \in \mathbb{N} \). Let \( H \) be the set of functions \( h : \mathbb{N}_0 \to P \) and \( G \) the set \( H \times G_2 \) where \( G_2 \) are the functions \( g : \mathbb{N}_0 \to \mathbb{N}_0 \) satisfying \( g(0) = 0 \) and \( g(n) < n \) for all \( n \in \mathbb{N} \). The semi group structure is given by
\[ (f_1, g_1) \circ (f_2, g_2) = (f_1 f_2 \circ g_1, g_2 \circ g_1) \]
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and the operation on $H$ via $(f,g)\in h = fh \circ g$.

The interpretation of $(f,g) \in G$ is as a map on $H$ with $f$ is a multiplicative factor and $g$ an index transformation. The operation * corresponds to the convolution of maps on $H$. Since $H$ is a vector space we may enlarge $G$ naturally to a vector space.

Consider the binary tree $V$ and let $U^v, v \in V$ be independent rvs with a uniform distribution. Let $I_n^v = \left\lfloor nU^v \right\rfloor$ (upper Gauss bracket) and define the transformations on the edges $(v,v1), (v,v2)$ by

$$J_1^v(n) = I_n^v - 1 \quad J_2^v(n) = n - I_n^v$$

$$T_1^v(n) = \left(\frac{J_1^v(n)}{n}, J_1^v(n)\right) \quad T_2^v(n) = \left(\frac{J_2^v(n)}{n}, J_2^v(n)\right)$$

and the vertex weight $C^v(n) = C_n(I_n^v)$.

The random variables $R^v_m := \sum_{w \in V_c} L^w \cdot C^w$ converge as $m \to 0$ a.e. and in $L_2$ to a limit $R^v_m$ and satisfy

$$R^v_m = \sum_i T^v_i \cdot R^v_{m-1} + C^v$$

for $m \in \mathbb{N} = \mathbb{N} \cup \{\infty\}$. Notice the connection to the previous description, $Y_n = R^v_m(n)$.

$R^v_m(n)$ converge for every $v \in V$ in $L_2$ to the rv $Q^v$ from the Quicksort example [7]. We shall use $Q^v = R^v_m(n)$ in the sequel.

It is worth while to put the two examples together. Use $\mathbb{N}_0 = \mathbb{N} \cup \{\infty\}$ instead of $\mathbb{N}$ in the second example and incorporate the first example via the value $\infty$.

For later purpose we establish a general Lemma. Let $(V = [1,2]^n, T = (U,1-U), (P_{\alpha},\cdot))$ be a WBP without costs. Let $U$ have a uniform distribution. Let $0 \leq C_n, n \in \mathbb{N}_0, v \in V$ be a sequence of positive real rvs. Let $X_0^v, v \in V$ be rvs and define $X_n^v, v \in V, n \in \mathbb{N}$ by

$$X_n^v = (U^v X_{n-1}^v) \vee ((1-U^v) X_{n-1}^v) + C_n^v$$

**Lemma 3.1** Assume for $p > \ln 2 \gg \sup_{v \in V} \|C_n^v\|_p \to 0$. Then $X_n^v$ converges as $n \to \infty$ a.e. to 0 for all $v \in V$.

Proof. Let $M^v_n = \sup_{w \in v \cap n} L^w$. We intend to use a result of Biggins [9] $\frac{\ln M^v_n}{n}$ converges as $n \to \infty$ to some $a \in P$ where $a$ is uniquely determined by $I(a) = 0$. The function $I(x) = \inf_{\alpha \in P} (\ln m(\alpha) - x\alpha)$ is the Fenchel-Legendre Transform of the the convex function $P_+ \ni \alpha \mapsto \ln m(\alpha)$ where $m(\alpha) = E \sum_{n=0}^\infty (T^\alpha_n)^\alpha$. In our case $m(\alpha) = \frac{1}{\alpha + 1}$. The minimum of the function $P_+ \ni \alpha \mapsto (\ln m(\alpha) - x\alpha)$ is attained at $\alpha = \alpha(x)$ with $\frac{-1}{\alpha + 1} - x = 0$. We obtain $I(x) = \ln(-x) - x\alpha(x) = \ln x + x - 1$.

Therefore $I(a) = 0 \leftrightarrow e = e^{\alpha + a}$. The solution $a = -1$ is uniquely determined. The assumptions of Biggins result are satisfied. For given $0 < \varepsilon < p - 2 \ln 2$ let $n_0^v = n_0^v(\omega)$ be such that for all $n \geq n_0^v$ $M^v_n \leq e^{(a + \varepsilon)n}$.

By induction we obtain

$$X_n^v \leq C^v_{n^0} + \vee_{j=0}^{n-1} T^v_j C^v_{n-j} \leq \sum_{j=0}^{n-1} \vee_{w \in V_j} L^w \cdot e^{\varepsilon w}$$

We shall use for some $n_j$ sufficiently large

$$X_n^v \leq C^v_{n^0} + \vee_{j=0}^{n-1} T^v_j C^v_{n-j} \leq \sum_{j=0}^{n-1} L^w \cdot e^{\varepsilon w} + \sum_{j=0}^{n-1} L^w \cdot e^{\varepsilon w}.$$
The first sum converges a.e. to 0 for every \( n_1 \) and \( v \in V \).

For the second let \( 0 < \varepsilon_n \) satisfy \( \sum \varepsilon < \infty \). We intend to use Borel-Cantelli for the sequence

\[
D^n_j = \{ \mu_j \leq e^{(a+\varepsilon)p} \sum_{v \in V} \lambda_j C_{n-j}^v \geq \varepsilon_j \}
\]

\[
P(D^n_j) \leq \sum_{v \in V} \frac{E(C_{n-j}^v)^p}{e^{(a+\varepsilon)p} \varepsilon_j^p}
\]

\[
\leq e^{(\ln 2+ap+q)p/j} \frac{C}{\varepsilon_j^p}
\]

where \( C \) is the finite constant \( \sup_{n \sup_{v \in V}} \| C_n^v \|_p \rightarrow 0 \). Since \( \sum_j P(D^n_j) < \infty \) the events \( D^n_j \) appear only finitely often for every \( v \in V \). We conclude

\[
\sum_{j=0}^{n-1} \sum_{v \in V} \lambda_j C_{n-j}^v \leq \sum_{j=0}^{n-1} \varepsilon_j + \sum_{j=0}^{n-1} 1_{b_j} \sum_{v \in V} \lambda_j C_{n-j}^v < \infty.
\]

The first term on the right side is arbitrary small for sufficiently large \( n_1 \). The second term converges to 0 a.e. if \( n_1 \) converges to \( \infty \). This concludes the statement.

**IV. THE QUICKSORT PROCESS**

In this section we specify the Partial Quicksort process by using the weighted branching process. For the number of comparisons obtained by the Partial Quicksort \( X(n,l) \), we suggest the normalization

\[
Y^n(l) := \frac{X(n,l) - a(n,l)}{n}
\]  

(21)

Assume for simplicity that the rank of the pivot \( I(n,l) \) is uniformly distributed random variable. The distribution depending only on \( l \) and on the size of the list \( n \), we obtain a recursion given by the following Lemma [10].

**Lemma 4.1**

\[
Y^n(l) = 1_{r_1 \geq l} \left( 1_{r_1 < l} \frac{l-1}{n} Y^n(n-1) + \frac{n-l}{n} Y^n(n-l) \right) + 1_{r_1 = l} \frac{l-1}{n} \frac{l-1}{l-1} + \frac{n-l}{n} Y^n(n-l) + \frac{l-1}{n}
\]  

(22)

where

\[
C^n(l) = \frac{n-l}{n} \frac{n-l}{n} \frac{a(n,l)}{n} + 1_{r_1 \geq l} \left( \frac{a(l-1)}{n} \frac{a(l-1)}{n} + \frac{a(n-l, l-1)}{n} \right)
\]  

(23)

In the next lemma we will give an explicit formula of the cost function \( C(n,l,i) \). For the proof we need the well known properties of the \( n \)-th harmonic number [1].

**Lemma 4.2** The function \( C \) as defined in (13) has the explicit representation

\[
C(n,l,i) = 2 \frac{i}{n+1} (H_n - H_{n+1}) + 2(1 - \frac{i}{n+1}) (H_{n+1} - H_{n+1}) + 2(1 - \frac{i}{n+1}) (H_{n+1} - H_{n+1})
\]

\[
- (1 - \frac{i}{n+1}) (H_n - H_{n+1}) - H_{n+1} + (n + 3 - l) (H_{n+1} - H_{n+1})
\]

\[-n + i - 2 + \frac{1}{(n+1)(i+1+l)} - \frac{1}{(n+1)(n+2)}.
\]

Proof. From the equation above and using the properties of the \( n \)-th harmonic number we have
\[(n + 1)C(n, l, i) = n - 1 - a(n, l) + \sum \lambda(i, l, i) + 1 = \lambda(i - 1, l - 1) + 1 = \lambda(i, l, i) + a(n - i, l - i)\]

\[= -n - 1 - 2(n + 1)H_n + (n + 3 - l)H_{n+1} + 6l - 6 + \sum \lambda(i, l, i) + 2iH_{i-1} - 2(i + 2 - l)H_{i-1} - 6l + 6\]

\[\quad + \sum \lambda(i, l, i) + 2(i - 1) + 2 \lambda(i, l, i) - 2(n + 3 - l)H_{n+1} - 6(l - i) + 6\]

\[= 2iH_i + 2(n + 1 - i)H_{n+1} + 2n + 1 + 2 \lambda(i, l, i) - 2(i + 2 - l)H_{i-1} - (n + 3 - l)H_{n+1} + (n + 3 - l)H_{n+1}\]

\[= 2iH_i + 2(n + 1 - i)H_{n+1} + 2n + 1 + 2 \lambda(i, l, i) - 2(i + 2 - l)H_{i-1} - (n + 3 - l)H_{n+1} + (n + 3 - l)H_{n+1}\]

\[\quad + (n + 3 - l)H_{n+1} - n - i + 2 + \frac{1}{i+1 - l} - \frac{1}{n + 1 + l}.\]

Let \(D\) be the vector space of cadlag functions \(f : [0, 1] \to \mathbb{P}\) (right continuous with existing left limits). \(D\) is endowed with the Skorohod topology induced by the Skorohod \(J_1\)-metric

\[d(f, g) = \inf \{\varepsilon > 0 \mid \exists \lambda \in \Lambda : \|f - g \circ \lambda \| \leq \varepsilon, \|\lambda - id\| \leq \varepsilon\}, \quad (24)\]

where \(\Lambda\) is the set of all bijective increasing functions \(\lambda : [0, 1] \to [0, 1]\). We use the supremum norm \(\|f\| = \sup |f(t)|\). The space \((D, d)\) is a separable, non complete metric space, but a polish space [9]. The \(\sigma\)-field \(\sigma(D)\) is the Borel-\(\sigma\)-field via the Skorohod metric. The \(\sigma\)-field is isomorphic to the product \(\sigma\)-field \(\mathbb{R}_A \cap D\) where \(A\) is a dense subset of \([0, 1]\) containing the 1.

Let \(F(D)\) be the space of all measurable functions \(X\) with values in \(D\). For \(1 \leq p < \infty\) let \(F_p(D)\) be the subspace such that

\[\|X\|_{\infty, p} := \|X\|_p < \infty\]

is finite. Here \(\|\cdot\|_p, p < \infty\), denotes the usual \(L_p\)-norm for rvs. The map \(\|\cdot\|_{\infty, p}\) is a pseudo metric on \(F_p(D)\). Let \(\sim\) be the common equivalence relation

\[X \sim Y \iff P(X \neq Y) = 0\]

and \(F_p(D)\) be the set of equivalence classes \([X] = \{Y \in F(D) \mid X \sim Y\}\) intersected with \(F_p(D)\). Then it is well known

**Proposition 4.1** For \(1 \leq p < \infty\) is \((F_p(D), \|\cdot\|_{\infty, p})\) a Banach space with the usual addition and multiplication

\[\|f + g\|_{\infty, p} = \|f\|_{\infty, p} + \|g\|_{\infty, p}\]

Let \(D_t\) be the subset of all functions \(f : [0, 1] \to [0, 1]\) in \(D\) such that there exists \(0 = t_0 < t_1 < \cdots < t_r = 1\) satisfying \(f\) is increasing on the interval \([t_{i-1}, t_i)\) for \(i = 1, 2, \cdots, r\). In the following we consider the composition of random variables and give some results needed in our work.

**Lemma 4.3** Let \(X\) be a random variable with values in \(D\) and let \(B\) be a random variable with values in \(D_t\). Then \(X \circ B\) is a random variable with values in \(D_t\).

Proof. Let \(X : \Omega \to D\), and \(B : \Omega \to D_t\). Since for all \(\omega \in \Omega\), \(B(\omega) \in D_t\), then the function \((X \circ B)(\omega) \in D\).

It is sufficient to show \(X \circ B(t) : \Omega \to \mathbb{P}\) is measurable for all \(t \in [0, 1]\). For all \(t \in [0, 1]\) define \(B_j : \Omega \to \mathbb{P}\), \(j \in \mathbb{N}\) by \(B_j(\omega) := \frac{[B(\omega)(t)]}{j}\). We will approximate the \(X \circ B\) by the random variables \(X \circ B_j\)

using the discretization on the values \(0, \frac{1}{j}, \frac{2}{j}, \cdots, 1 - \frac{1}{j}\). \(B_j(t)\) is a measurable for all \(\omega \in \Omega\) since

\[\left(B_j(t)\right)^{\downarrow}((a, 1)) = (B(t))^{\downarrow}\left([\frac{a}{j}, 1]\right) \in \Lambda,\]

for all \(j \in \mathbb{N}\) and \(t \in [0, 1]\). By the definition of \(B_j\), \(B_j(\omega) \geq B(\omega)(t)\) and \(\lim_{j} B_j(\omega) = B(\omega)(t)\). Furthermore
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\[ X \ast B(\omega(t)) = X(\lim_{j} B_j(\omega(t))) = \lim_{j} X(B_j(\omega(t))) = \lim_{j} (X \ast B_j(\omega(t))) \]

Then \( \lim_{j \to \infty} (X \ast B_j(t)) \) is measurable since \( X \ast B_j(t) \) is measurable. This implies that \( X \ast B(t) \) is measurable for all \( t \in [0,1] \) with respect to \( B(P) \).

V. MODEL DESCRIPTION

Let \( G := D \times D_1 \) and let \( H := D \). For all \( f, f_1, f_2 \in D \) and \( g, g_1, g_2 \in D_1 \) define the operation \(* : G \times G \to G \) by

\[
*((f_1, g_1),(f_2, g_2)) := (f_1 \ast g_1)^*(f_2, g_2)
\]

where \( \circ \) denotes the convolution and \( \ast \) is the pointwise multiplication in \( D \). For all \( f, f_1, h \in D \) and \( g, g_1 \in D_1 \), define the operation \( \otimes : G \times H \to H \) by

\[
\otimes((f, g), h) := (f, g) \otimes h = f \cdot h \ast g.
\]

For all \( f, f_1, f_2, f', f_2, f_1', f_2' \in D \), the operation \( \ast \) is bilinear in the first coordinate on \( D \times D_1 \),

\[
(f_1 + f_2, g)^* (f', g') = (f_1, g)^* (f', g') + (f_2, g)^* (f', g'),
\]

\[
(f, g)^* (f_1' + f_2', g') = (f_1, g)^* (f', g') + (f, g)^* (f_2', g').
\]

And for all \( f, f_1', f_2', h \in D \), \( g, g_1, g_2, g_1' \in D_1 \),

\[
(f_1 + f_2) \otimes h = (f_1, g) \otimes h + (f_2, g) \otimes h,
\]

\[
(f, g) \otimes (h_1 + h_2) = (f, g) \otimes h_1 + (f, g) \otimes h_2.
\]

The tuple \((f, g) \in G\) has the interpretation of a map \( M_{f,g} : H \to H \) acting as

\[
(M_{f,g}(h))(t, n) = f(t, n) h(g(t, n)).
\]

The first coordinate \( f \) is a space transformation and the second coordinate \( g \) is a time and index transformation. The semigroup structure \( \ast \) is the composition of the corresponding maps. Since \( H \) is a vector space and \( P \) is a lattice, we will embed \( G \) to maps \( H^H \) and use freely the induced structures \( +, \cdot \) and \( \vee \).

\[
(M_{f,g} + M_{f_1, g_1})(h) = M_{f,g}(h) + M_{f_1, g_1}(h), \quad a \cdot (M_{f,g})(h) = (a \cdot M_{f,g})(h), \quad (M_{f,g} \vee M_{f_1, g_1})(h) = ((M_{f,g})(h)) \vee (M_{f_1, g_1}(h)).
\]

It is easy to see the equation (26) as follow

\[
M_{f,g} \circ M_{f_1, g_1}(h)(t, n) = M_{f,g}(f_1(t, n), h(g_1(t, n)))
\]

\[
= f(t, n) \cdot (f_1, h(g_1))(g(t, n))
\]

\[
= f(t, n) f_1(g(t, n)) h(g_1(t, n))
\]

\[
= M_{f_1, g_1}(f_1(t, n), h(g_1(t, n)))(t, n).
\]

We notice here, the sorting partitioning strategy suggests a binary tree. Consider the binary tree \( V = \{1,2\}^N \).

For \( v = v_1 v_2 \cdots v_n \in \zeta \), \( n \in \mathbb{N} \) and for \( m \in \mathbb{N} \), \( m \leq n \), \( v^m = v_1 v_2 \cdots v_m \) denote to the \( m \)-th coordinate of \( v \). Let \( U^v : \Omega \to [0,1], v \in V \) be independent and identically uniformly distributed random variables on the unit interval \([0,1]\). Let \( Q^v, v \in V \) be the random variable has a limiting Quicksort distribution.

Define a map \( T^v : \Omega \to G \), the weights on the edges \((v, v^i), v \in \zeta, i \in \{1,2\}\) by

\[
T^v := (A^v, B^v)
\]

for all \( v \in V \) and \( T^v := (T^v_1, T^v_2, 0, \cdots) \). For all \( v \in V \), define the following parameters

\[
A^v_1(t) := \frac{1}{U^v_{st}} U^v,
\]

\[
A^v_2(t) := \frac{1}{U^v_{st}} (1 - U^v),
\]

\[
A^v_3(t) := 0 = A^v_4(t) = \cdots
\]

\[
B^v_i(t) := \left( \frac{1}{U^v} \land 1 \right)_{t \in [0,1]}
\]

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Define a map $C^v : \Omega \to H$, the vertex weight by
\[ C^v := C(U^v,v) + U^v Q^1, \]
where $C$ is given in (23). Here $\left(A^v, B^v, C^v \right) v \in V$ in terms of $U^v$ are iid copies of $(A,B,C)$. The edge weight $T^v$ attached to the edge $(v,v)$ is given by $\left(A^v, B^v \right)$. The tuple $\left(V, (T^v, C^v)_{v \in V}, (G_i,*, H, \otimes) \right)$ is a weighted branching process. Consider the weighted branching process as given above and for all $v \in \zeta$, define the sequence
\[ R^v_0 := \sum_{\omega \in \zeta \otimes \omega} L^v_\omega \otimes C^v_\omega, \quad R^v_0 = 0, \]
where the family of path weights $L^v := (L^v_\omega)_{\omega \in \omega}$ from the node $v$ is given recursively by (14).

**Lemma 5.1** Let $U$ be a uniformly distributed random variable on $[0,1]$ and $C$ defined as in (29). Then for all $t \in [0,1]$ $E(C) = 0$ and $\text{Var}(C) < \infty$.

**Proof.** $\int_0^1 u \ln u du + \int_0^1 (1 + uQ + 2(1-u)\ln(1-u))du + \int_0^1 (2u-1 + 2(1-t)\ln(1-t) - 2(u-t)\ln(u-t))du.$

It follows
\[ \int_0^1 u \ln u du = \int_0^1 u^2 (\ln u)^3 du = -\frac{1}{4}, \]
\[ \int_0^1 (1-u)^2 (\ln(1-u))^2 du = \frac{2}{27}, \]
\[ \int_0^1 (1-u)\ln(1-u)du = \frac{1}{2} \left( t^2 \ln t - \frac{1}{2} t^2 \right), \]
\[ \int_0^1 u-t)\ln(u-t)du = \frac{1}{2} \left( t^2 \ln t - \frac{1}{2} t^2 \right), \]
\[ \int_0^1 (t-u)\ln(t-u)du = \frac{1}{2} \left( t^2 \ln t - \frac{1}{2} t^2 \right), \]
and
\[ \int_0^1 u(1-u)(\ln u)\ln(1-u)du = \frac{1}{108} \left( 37 - 3\pi^2 \right) \approx 0.068437 < 1. \]

Therefore $E(C) = 2 \int_0^1 u \ln u du + \int_0^1 (1 + uQ + 2(1-u)\ln(1-u))du = 0.$

Moreover
\[ E(C^2) < 1 + 4 \int_0^1 u \ln u du + 4 \int_0^1 u^2 (\ln u)^2 du + 4 \int_0^1 (1-u)^2 (\ln(1-u))^2 du \]
\[ + 4 \int_0^1 (1-u)\ln(1-u)du + \frac{1}{3} E(Q^2) < \infty. \]

**Lemma 5.2** The random variables $R^v_m$ defined as in (30) satisfies the backward recursion
\[ R^v_m = \sum_{i=1}^{m} T^v_i \otimes R^v_{m-1} + C^v \]
for all $v \in \zeta$ and $m \in \mathbb{N}$.

**Proof.** The sum $R^v_m$ is well defined and by equations (30), we have
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\[ R_m^v = \sum_{1 \leq k \leq m} (T_{w_1}^v \ast T_{w_2}^v \ast \ldots T_{w_k}^v) \otimes C^{\ast v} \]

\[ = \sum_{k=0}^{m} \sum_{i \in v_k} (T_{w_1}^v \ast T_{w_2}^v \ast \ldots T_{w_k}^v) \otimes C^{\ast v} \]

\[ = C^v + \sum_{k=0}^{m} \sum_{i \in v_k} (T_{i}^v \ast T_{i-1}^v \ast \ldots T_{i-k}^v) \otimes C^{\ast v} \]

\[ = C^v + \sum_{i=1}^{m} T_{i}^v \ast (\sum_{k=1}^{m} T_{i-1}^v \ast \ldots T_{i-k}^v) \otimes C^{\ast v} \]

The connection between the operator \( K \) and the weighted branching process \( R \), in the case of the Partial Quicksort is given by the following Corollary.

**Corollary 5.1** Let the starting measure \( \mu_0 \) be the point measure on the function \( \varnothing \in D \) identical \( 0 \). Then the random variables \( R_n \) defined as in (30) satisfies

\[ R_{n+1} = C^\varnothing + \sum_{i \in N} A_i^\varnothing \cdot R_i^\varnothing \otimes B_i^\varnothing, \]

where \( R_i^\varnothing \) denotes the random variable \( R_i \) for the tree with root \( i \). The distribution of \( R_n \) is \( K^\varnothing(\mu_0) \).

Proof. In the positive case all \( R_n \) and \( n \)-fold iterates \( K^\varnothing(\mu_0) \) are well defined [3]. By Lemma 5.2, the sequence \( R_n \) satisfies the backward recursion

\[ R_{n+1} = C^\varnothing + \sum_{i \in N} T_i^v \otimes R_i^v. \]

If \( T_i^v := (A_i^v, B_i^v) \) for all \( v \in V, i \in N \) and \( T^v = (T_1^v, T_2^v) \), then we have

\[ R_n = C^\varnothing + \sum_{i \in N} (A_i^\varnothing, B_i^\varnothing) \otimes R_i^\varnothing = C^\varnothing + \sum_{i \in N} A_i^\varnothing \cdot R_i^\varnothing \otimes B_i^\varnothing. \]

To prove the distributional result on \( R_n \) we use the mathematical induction on \( n \). The induction base case when \( n = 1 \) is true since \( R_1 = C^\varnothing \) has the distribution \( K(\mu_0) \). For the inductive step \( n \) to \( n+1 \) argue by the backward recursion

\[ R_{n+1} = C^\varnothing + \sum_{i \in N} A_i^\varnothing \cdot R_i^\varnothing \otimes B_i^\varnothing = K(A(R_n)) = K(K^\varnothing(\mu_0)) = K^{n+1}(\mu_0). \]

Here the random variables \( (A_i^\varnothing, B_i^\varnothing, C^\varnothing) R_i^\varnothing, i \in N \) are independent. For all \( v \in V, n \in N \) define \( S_n^v : \Omega \rightarrow D \) by

\[ S_n^v := \sum_{1 \leq k \leq n} T_{w_k}^v \otimes C^{\ast v}, \]

\[ S_0^v = C^v. \]

The equation (32) defines the total weight in the \( n \)-th generation. Our interest concentrates on the total weight (cost) regard up to the \( n \)-th generation. From equations (32) and (16), we have

\[ S_n^v = R_{n+1}^v - R_0^v \]

Now, it is easy to show that for all \( \omega \in \Omega \) and \( S_n(\omega) \in D \),

\[ S_n^v = \sum_{i \in N} T_i^v \ast S_{n-1}^v \]

where \( T_i \) and \( S_n^i \) and \( S_n^2 \) are the \( S_n \) random variable for the tree with root \( i \). Using the equation (33) and (34), for all \( t \in [0,1] \) we obtain

\[ S_n^v(t) = \sum_{i \in N} (A_i^\varnothing \cdot S_{n-1}^v \otimes B_i^\varnothing)(t) = (A_1^\varnothing \cdot S_{n-1}^v \otimes B_1^\varnothing + A_2^\varnothing \cdot S_{n-1}^2 \otimes B_2^\varnothing)(t) \]

and therefore
\[ S'_n(t) = \sum_{i=0}^{n-1} U_i S^{iv}_{n-1}(\frac{1}{U}) + \sum_{i=0}^{n-1} T_i S^{iv}_{n-1}(\frac{1}{1-U}). \] (35)

**Lemma 5.3** Let \( S'_n, n \in \mathbb{N}, v \in \mathbb{Z} \) be as above. Then for all \( n \in \mathbb{N}, \) \( E[\|S'_n\|_\infty] = 0 \) and \( \text{Var}(\|S'_n\|_\infty) \) converges exponentially fast to 0, as \( n \to \infty \).

**Proof.** Notice \( (S'_n) \stackrel{D}{=} (S^v'_n) \). By equation (35)

\[ \|S'_n\|_{2,D} = \bigg\| \sum_{i=0}^{n-1} U_i S^{iv}_{n-1}(\frac{1}{U}) + \sum_{i=0}^{n-1} (1-U) S^{iv}_{n-1}(\frac{1}{1-U}) \bigg\| \]

All mixed terms are zero. The first term is

\[ E\sup_t \left( \sum_{i=0}^{n-1} U_i S^{iv}_{n-1}(\frac{1}{U}) \right)^2 \leq E(U^2) E\left( \left\| S^{iv}_{n-1} \right\|_{\infty}^2 \right) \]

And the second term is

\[ E\sup_t \left( \sum_{i=0}^{n-1} (1-U) S^{iv}_{n-1}(\frac{1}{1-U}) \right)^2 \leq E((1-u)^2) E\left( \left\| S^{iv}_{n-1} \right\|_{\infty}^2 \right) \]

Then we have

\[ \|S'_n\|_{2,D} \leq \left( EU^2 + E(1-U)^2 \right) E\left( \left\| S^{iv}_{n-1} \right\|_{\infty}^2 \right) \leq \frac{2}{3} E\left( \left\| S^{iv}_{n-1} \right\|_{\infty}^2 \right). \]

For \( n \in \mathbb{N}_0 \) let \( b_n := \|S^{iv}_{n-1}\|_{2,D} \). Notice \( b_n \) does not depend on the vertex \( v \). Then \( b_n^2 \leq \frac{2}{3} b_{n-1}^2 \) and therefore by iteration of the inequality \( b_n^2 \leq \left( \frac{2}{3} \right)^n b_0^2 < \infty \). Where \( b_0 = \|S^{iv}_0\|_{2,D} = \|C(U,.)\|_{2,D} < \infty \).

Let \( A(t) := \sum_{i=0}^{n-1} |A_i(t)| \) for all \( t \in [0,1] \) and note that \( E[A_i] = E(U) + E(1-U) = 1 \) and

\[ \sum_{i=0}^{n-1} \left( \sum_{i=0}^{n-1} |A_i(t)| \right)^2 = EU^2 + E(1-U)^2 = 2E(U^2) = \frac{2}{3} < 1. \]

**Lemma 5.4** For fixed \( t \in [0,1] \) and \( n \in \mathbb{N}, \) \( \text{Var}(R_n(t)) \) converges exponentially fast to 0, as \( n \to \infty \).

**Proof.** The random variables \( S_j, j \in \mathbb{N} \) are pointwise well defined and measurable. By Theorem 5.3 we have

\[ E[R_n(t)^2] = E\left( \sum_{i=0}^{n-1} S_j(t)^2 \right) = E\left( \sum_{i=0}^{n-1} S_j(t) S_j(t) \right) = \sum_{i=0}^{n-1} E(S_j(t) S_j(t)) \]

By the Cauchy-Schwarz inequality, \( S_j(t) S_j(t) \) is integrable. For \( i, j \in \mathbb{N} \) and \( i \leq j \), define

\[ B_i := \sigma\left( \left\{ T^v, C^v \right\} \bigg| \sigma_i \right) \]

By conditional expectation we have for \( i \leq j \)

\[ E[S_j(t) S_j(t)] = E[E[S_j(t) S_j(t) \bigg| B_i]] = E[S_j(t) E[S_j(t) \bigg| B_i]] = 0 \]

Therefore \( E[R_n(t)^2] = \sum_{i=0}^{n-1} E[(S_i(t))^2] \)

And therefore Lemma 5.3 finishes the proof of the following main result.
Theorem 5.1 Let \((V, (T_1, T_2), C, (G, \ast), (H, \emptyset))\) be the weighted branching process defined as above. Then \(R_n^v\) converges uniformly as \(n \to \infty\) almost everywhere in \(D\) to a random variable \(R^v\) for all \(v \in \zeta\). The family \(R^v, v \in \zeta\) satisfies

\[
R^v = \sum_{i=1}^{2} T_i^v R^v + C^v
\]

almost everywhere. Moreover, for every \(p > 1\) holds

\[
\left\| R^v \right\|_p \leq \frac{8 + \left( \frac{1}{p+1} \right)^p \left\| Q \right\|_p}{1 - k_p}
\]

where \(k_p = \left( \frac{2}{p+1} \right)^p\) and \(Q\) is a random variable with the Quicksort distribution.

REFERENCES


*Mahmoud Ragab. “Running time Analysis of Sorting Algorithm via an Asymptotic Distribution.”