

Unique Common Fixed Point Theorem for Three Pairs of Weakly Compatible Mappings Satisfying Generalized Contractive Condition of Integral Type

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Abstract: We prove some unique common fixed point result for three pairs of weakly compatible mappings satisfying a generalized contractive condition of Integral type in complete G-metric space. The present theorem is the improvement and extension of Vishal Gupta and Naveen Mani [5] and many other results existing in literature.

Keywords: Fixed point, Complete G-metric space, G-Cauchy sequence, Weakly compatible mapping, Integral Type contractive condition.

I. Introduction

Generalization of Banach contraction principle in various ways has been studied by many authors. One may refer Beg I. & Abbas M.[2], Dutta P.N. & Choudhury B.S.[3], Khan M.S., Swaleh M. & Sessa, S.[9], Rhoades B.E.[12], Sastry K.P.R. & Babu G.V.R.[13], Suzuki T.[15], Alber Ya.I. & Guerre-Delabriere S. [1] had proved results for weakly contractive mapping in Hilbert space, the same was proved by Rhoades B.E.[12] in complete metric space.

Jungck G.[6] proved a common fixed point theorem for commuting mappings which is the extension of Banach contraction principle. Sessa S.[14] introduced the term "Weakly commuting mappings" which was generalized by Jungck G.[6] as "Compatible mappings". Pant R.P.[11] coined the notion of "R-weakly commuting mappings", whereas Jungck G. & Rhoades B.E. [8] defined a term called "weakly compatible mappings" in metric space.

Fisher B. [4] proved an important Common Fixed Point theorem for weakly compatible mapping in complete metric space.

Mustafa in collaboration with Sims [10] introduced a new notation of generalized metric space called G-metric space in 2006. He proved many fixed point results for a self mapping in G-metric space under certain conditions.

Now we give some preliminaries and basic definitions which are used through-out the paper.

Definition 1.1: Let X be a non empty set, and let $G : X \times X \times X \rightarrow R^+$ be a function satisfying the following properties:

$$(G_1) \quad G(x, y, z) = 0 \text{ if } x = y = z$$

$$(G_2) \quad 0 < G(x, x, y) \text{ for all } x, y \in X, \text{ with } x \neq y$$

$$(G_3) \quad G(x, x, y) \leq G(x, y, z) \text{ for all } x, y, z \in X, \text{ with } y \neq z$$

$$(G_4) \quad G(x, y, z) = G(x, z, y) = G(y, z, x) \quad (\text{Symmetry in all three variables})$$

$$(G_5) \quad G(x, y, z) \leq G(x, a, a) + G(a, y, z), \text{ for all } x, y, z, a \in X \quad (\text{rectangle inequality})$$

Then the function G is called a generalized metric space, or more specially a G-metric on X , and the pair (X, G) is called a G-metric space.

Definition 1.2: Let (X, G) be a G-metric space and let $\{x_n\}$ be a sequence of points of X , a point $x \in X$ is said to be the limit of the sequence $\{x_n\}$, if $\lim_{n,m \rightarrow +\infty} G(x, x_n, x_m) = 0$, and we say that the sequence $\{x_n\}$ is G-convergent to x or $\{x_n\}$ G-converges to x .

Thus, $x_n \rightarrow x$ in a G - metric space (X, G) if for any $\epsilon > 0$ there exists $k \in \mathbb{N}$ such that $G(x, x_n, x_m) < \epsilon$, for all $m, n \geq k$

Proposition 1.3: Let (X, G) be a G - metric space. Then the following are equivalent:

- i) $\{x_n\}$ is G - convergent to x
- ii) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow +\infty$
- iii) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow +\infty$
- iv) $G(x_n, x_m, x) \rightarrow 0$ as $n, m \rightarrow +\infty$

Proposition 1.4 : Let (X, G) be a G - metric space. Then for any x, y, z, a in X it follows that

- i) If $G(x, y, z) = 0$ then $x = y = z$
- ii) $G(x, y, z) \leq G(x, x, y) + G(x, x, z)$
- iii) $G(x, y, y) \leq 2G(y, x, x)$
- iv) $G(x, y, z) \leq G(x, a, z) + G(a, y, z)$
- v) $G(x, y, z) \leq \frac{2}{3} (G(x, y, a) + G(x, a, z) + G(a, y, z))$
- vi) $G(x, y, z) \leq (G(x, a, a) + G(y, a, a) + G(z, a, a))$

Definition 1.5: Let (X, G) be a G - metric space. A sequence $\{x_n\}$ is called a G - Cauchy sequence if for any $\epsilon > 0$ there exists $k \in \mathbb{N}$ such that $G(x_n, x_m, x_l) < \epsilon$ for all $m, n, l \geq k$, that is $G(x_n, x_m, x_l) \rightarrow 0$ as $n, m, l \rightarrow +\infty$.

Proposition 1.6: Let (X, G) be a G - metric space .Then the following are equivalent:

- i) The sequence $\{x_n\}$ is G - Cauchy;
- ii) For any $\epsilon > 0$ there exists $k \in \mathbb{N}$ such that $G(x_n, x_m, x_m) < \epsilon$ for all $m, n \geq k$

Proposition 1.7: A G - metric space (X, G) is called G -complete if every G -Cauchy sequence is G - convergent in (X, G) .

Proposition 1.8: Let (X, G) be a G - metric space. Then the function $G(x, y, z)$ is jointly continuous in all three of its variables.

Definition 1.9 : Let f and g be two self – maps on a set X . Maps f and g are said to be commuting if $fgx = gfx$, for all $x \in X$

Definition 1.10 : Let f and g be two self – maps on a set X . If $fx = gx$, for some $x \in X$ then x is called coincidence point of f and g .

Definition 1.11: Let f and g be two self – maps defined on a set X , then f and g are said to be weakly compatible if they commute at coincidence points. That is if $fu = gu$ for some $u \in X$, then $fgu = gfu$.

The main aim of this paper is to prove a unique common fixed point theorem for three pairs of weakly compatible mappings satisfying Integral type contractive condition in a complete G – metric space.

The result is the extension of the following theorem of Vishal Gupta and Naveen Mani [5].

II. Theorem

Let S and T be self compatible maps of a complete metric space (X, d) satisfying the following conditions

- i) $S(X) \subset T(X)$
- ii)
$$\psi \int_0^{d(Sx, Sy)} \varphi(t) dt \leq \psi \int_0^{d(Tx, Ty)} \varphi(t) dt - \phi \int_0^{d(Tx, Ty)} \varphi(t) dt$$

for each $x, y \in X$ where $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is a continuous and non decreasing function and $\phi : [0, +\infty) \rightarrow [0, +\infty)$ is a lower semi continuous and non decreasing function such that $\psi(t) = \phi(t) = 0$ if and only if $t = 0$ also $\varphi : [0, +\infty) \rightarrow [0, +\infty)$ is a “Lebesgue-integrable function” which is summable on each

compact subset of R^+ , nonnegative, and such that for each $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$. Then S and T have a unique common fixed point.

III. MAIN RESULT

Theorem 2.1 : Let (X, G) be a complete G-metric space and $L, M, N, P, Q, R : X \rightarrow X$ be mappings such that

i) $L(X) \subset P(X)$, $M(X) \subset Q(X)$, $N(X) \subset R(X)$

ii)
$$\xi \left\{ \int_0^{G(Lx, My, Nz)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Px, Qy, Rz)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px, Qy, Rz)} f(t) dt \right\} \quad \text{-----(2.1.1)}$$

for all $x, y, z \in X$ where $\xi : [0, \infty) \rightarrow [0, \infty)$ is a continuous and non-decreasing function,

$\eta : [0, \infty) \rightarrow [0, \infty)$ is a lower semi continuous and non-decreasing function such that

$\xi(t) = \eta(t) = 0$ if and only if $t = 0$, also $f : [0, \infty) \rightarrow [0, \infty)$ is a Lebesgue integrable function

which is summable on each compact subset of R^+ , non negative and such that for each $\epsilon > 0$,

$$\int_0^\epsilon f(t) dt > 0$$

iii) The pairs (L, P) , (M, Q) , (N, R) are weakly compatible.

Then L, M, N, P, Q, R have a unique common fixed point in X.

Proof : Let x_0 be an arbitrary point of X and define the sequence $\{x_n\}$ in X such that

$$y_n = Lx_n = Px_{n+1}, \quad y_{n+1} = Mx_{n+1} = Qx_{n+2}, \quad y_{n+2} = Nx_{n+2} = Rx_{n+3}$$

Consider,

$$\begin{aligned} \xi \left\{ \int_0^{G(y_n, y_{n+1}, y_{n+2})} f(t) dt \right\} &= \xi \left\{ \int_0^{G(Lx_n, Mx_{n+1}, Nx_{n+2})} f(t) dt \right\} \\ &\leq \xi \left\{ \int_0^{G(Px_n, Qx_{n+1}, Rx_{n+2})} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px_n, Qx_{n+1}, Rx_{n+2})} f(t) dt \right\} \\ &= \xi \left\{ \int_0^{G(y_{n-1}, y_n, y_{n+1})} f(t) dt \right\} - \eta \left\{ \int_0^{G(y_{n-1}, y_n, y_{n+1})} f(t) dt \right\} \quad \text{-----(2.1.2)} \\ &\leq \xi \left\{ \int_0^{G(y_{n-1}, y_n, y_{n+1})} f(t) dt \right\} \end{aligned}$$

Since ξ is continuous and has a monotone property,

$$\therefore \int_0^{G(y_n, y_{n+1}, y_{n+2})} f(t) dt \leq \int_0^{G(y_{n-1}, y_n, y_{n+1})} f(t) dt \quad \text{-----(2.1.3)}$$

Let us take $\delta_n = \int_0^{G(y_n, y_{n+1}, y_{n+2})} f(t) dt$, then it follows that δ_n is monotone decreasing and lower bounded sequence of numbers.

Therefore there exists $k \geq 0$ such that $\delta_n \rightarrow k$ as $n \rightarrow \infty$. Suppose that $k > 0$

Taking limit as $n \rightarrow \infty$ on both sides of (2.1.2) and using that η is lower semi continuous, we get, $\xi(k) \leq \xi(k) - \eta(k) < \xi(k)$, which is a contradiction. Hence $k = 0$.

This implies that $\delta_n \rightarrow 0$ as $n \rightarrow \infty$ i.e. $\int_0^{G(y_n, y_{n+1}, y_{n+2})} f(t) dt \rightarrow 0$ as $n \rightarrow \infty$.------(2.1.4)

Now , we prove that $\{y_n\}$ is a G- Cauchy sequence. On the contrary , suppose it is not a G- Cauchy sequence.

\therefore There exists $\epsilon > 0$ and subsequences $\{y_{m(i)}\}$ and $\{y_{n(i)}\}$ such that for each positive integer i , $n(i)$ is minimal in the sense that , $G(y_{n(i)}, y_{m(i)}, y_{m(i)}) \geq \epsilon$ and $G(y_{n(i-1)}, y_{m(i)}, y_{m(i)}) < \epsilon$

$$\text{Now , } \epsilon \leq G(y_{n(i)}, y_{m(i)}, y_{m(i)}) \leq G(y_{n(i)}, y_{m(i-1)}, y_{m(i-1)}) + G(y_{m(i-1)}, y_{m(i)}, y_{m(i)}) < \epsilon + G(y_{m(i-1)}, y_{m(i)}, y_{m(i)}) \quad \text{-----(2.1.5)}$$

$$\text{Let } 0 < \alpha = \int_0^\epsilon f(t) dt \leq \int_0^{G(y_{n(i)}, y_{m(i)}, y_{m(i)})} f(t) dt \leq \int_0^{\epsilon + G(y_{m(i-1)}, y_{m(i)}, y_{m(i)})} f(t) dt$$

$$\text{Taking } i \rightarrow \infty , \text{ and using (2.1.4) , we get , } \lim_{i \rightarrow \infty} \int_0^{G(y_{n(i)}, y_{m(i)}, y_{m(i)})} f(t) dt = \alpha \quad \text{-----(2.1.6)}$$

Now , using rectangular inequality , we have

$$G(y_{n(i)}, y_{m(i)}, y_{m(i)}) \leq G(y_{n(i)}, y_{n(i-1)}, y_{n(i-1)}) + G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)}) + G(y_{m(i-1)}, y_{m(i)}, y_{m(i)}) \quad \text{----}$$

$$G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)}) \leq G(y_{n(i-1)}, y_{n(i)}, y_{n(i)}) + G(y_{n(i)}, y_{m(i)}, y_{m(i)}) + G(y_{m(i)}, y_{m(i-1)}, y_{m(i-1)}) \quad \text{----}$$

$$\therefore \int_0^{G(y_{n(i)}, y_{m(i)}, y_{m(i)})} f(t) dt \leq \int_0^{G(y_{n(i)}, y_{n(i-1)}, y_{n(i-1)}) + G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)}) + G(y_{m(i-1)}, y_{m(i)}, y_{m(i)})} f(t) dt$$

$$\text{and } \int_0^{G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt \leq \int_0^{G(y_{n(i-1)}, y_{n(i)}, y_{n(i)}) + G(y_{n(i)}, y_{m(i)}, y_{m(i)}) + G(y_{m(i)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt$$

Taking limit as $i \rightarrow \infty$ and using (2.1.4) , (2.1.6) we get

$$\int_0^{G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt \leq \alpha \leq \int_0^{G(y_{n(i-1)}, y_{n(i-1)}, y_{n(i-1)})} f(t) dt$$

$$\text{This implies that , } \lim_{i \rightarrow \infty} \int_0^{G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt = \alpha \quad \text{-----(2.1.9)}$$

Now , from (2.1.1) , we have ,

$$\xi \left\{ \int_0^{G(y_{n(i)}, y_{m(i)}, y_{m(i)})} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt \right\} - \eta \left\{ \int_0^{G(y_{n(i-1)}, y_{m(i-1)}, y_{m(i-1)})} f(t) dt \right\}$$

\therefore Taking limit as $i \rightarrow \infty$ and using (2.1.6) , (2.1.8) we will have , $\xi(\alpha) \leq \xi(\alpha) - \eta(\alpha) < \xi(\alpha)$

which is a contradiction. Hence we have $\alpha = 0$.

Hence $\{y_n\}$ is a G- Cauchy sequence. Since (X, G) is a complete G-metric space , there exists a point $u \in X$ such that $\lim_{n \rightarrow \infty} y_n = u$

$$\text{i.e. } \lim_{n \rightarrow \infty} Lx_n = \lim_{n \rightarrow \infty} Px_{n+1} = u , \lim_{n \rightarrow \infty} Mx_{n+1} = \lim_{n \rightarrow \infty} Qx_{n+2} = u , \lim_{n \rightarrow \infty} Nx_{n+2} = \lim_{n \rightarrow \infty} Rx_{n+3} = u$$

As $Lx_n \rightarrow u$ and $Px_{n+1} \rightarrow u$, therefore we can find some $h \in X$ such that $Qh = u$.

$$\therefore \xi \left\{ \int_0^{G(Lx_n, Mh, Mh)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Lx_n, Mh, Nx_{n+1})} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Px_n, Qh, Rx_{n+1})} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px_n, Qh, Rx_{n+1})} f(t) dt \right\}$$

$$\text{On taking limit as } n \rightarrow \infty , \text{ we get , } \xi \left\{ \int_0^{G(u, Mh, Mh)} f(t) dt \right\} \leq \xi(0) - \eta(0)$$

$$\therefore \xi \left\{ \int_0^{G(u, Mh, Mh)} f(t) dt \right\} = 0, \text{ which implies that } Mh = u.$$

Hence $Mh = Qh = u$ i.e. h is the point of coincidence of M and Q .

Since the pair of maps M and Q are weakly compatible, we write $MQh = QMh$ i.e. $Mu = Qu$.

Also, $Mx_{n+1} \rightarrow u$ and $Qx_{n+2} \rightarrow u$, \therefore we can find some $v \in X$ such that $Pv = u$.

$$\therefore \xi \left\{ \int_0^{G(Lv, Mx_{n+1}, Mx_{n+1})} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Lv, Mx_{n+1}, Nx_{n+2})} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Pv, Qx_{n+1}, Rx_{n+2})} f(t) dt \right\} - \eta \left\{ \int_0^{G(Pv, Qx_{n+1}, Rx_{n+2})} f(t) dt \right\}$$

$$\text{On taking limit as } n \rightarrow \infty, \text{ we get, } \xi \left\{ \int_0^{G(Lv, u, u)} f(t) dt \right\} \leq \xi(0) - \eta(0)$$

$$\therefore \xi \left\{ \int_0^{G(Lv, u, u)} f(t) dt \right\} = 0, \text{ which implies that } Lv = u. \text{ Hence we have } Lv = Pv = u \text{ i.e. } v \text{ is the point of}$$

coincidence of L and P . Since the pair of maps L and P are weakly compatible, we can write $LPv = PLv$ i.e. $Lu = Pu$.

Again, $Nx_{n+2} \rightarrow u$ and $Rx_{n+3} \rightarrow u$, therefore we can find some $w \in X$ such that $Rw = u$.

$$\therefore \xi \left\{ \int_0^{G(Lx_n, Mx_{n+1}, Nw)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Px_n, Qx_{n+1}, Rw)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px_n, Qx_{n+1}, Rw)} f(t) dt \right\}$$

$$\text{On taking limit as } n \rightarrow \infty, \text{ we get, } \xi \left\{ \int_0^{G(u, u, Nw)} f(t) dt \right\} \leq \xi(0) - \eta(0)$$

$$\text{i.e. } \xi \left\{ \int_0^{G(u, u, Nw)} f(t) dt \right\} = 0, \text{ which implies that } Nw = u.$$

Thus we get $Nw = Rw = u$ i.e. w is the coincidence point of N and R .

Since the pair of maps N and R are weakly compatible, we have $NRw = RNw$ i.e. $Nu = Ru$

Now, we show that u is the fixed point of L .

$$\text{Consider, } \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} = \xi \left\{ \int_0^{G(Lu, Mh, Nw)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Pu, Qh, Rw)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Pu, Qh, Rw)} f(t) dt \right\}$$

$$\therefore \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\}$$

$$\text{i.e. } \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\}$$

$$\text{i.e. } \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\} < \xi \left\{ \int_0^{G(Lu, u, u)} f(t) dt \right\}, \text{ which is a contradiction. } \therefore \text{ we get } Lu = u$$

$\therefore Lu = Pu = u$ i.e. u is fixed point of L and P .

Now, we prove that u is fixed point of M .

$$\text{Consider, } \xi \left\{ \int_0^{G(u, u, Mu)} f(t) dt \right\} = \xi \left\{ \int_0^{G(Lu, Mu, Nw)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Pu, Qu, Rw)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Pu, Qu, Rw)} f(t) dt \right\}$$

$$\therefore \xi \left\{ \int_0^{G(u, u, Mu)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(u, Mu, u)} f(t) dt \right\} - \eta \left\{ \int_0^{G(u, Mu, u)} f(t) dt \right\}$$

i.e. $\xi \left\{ \int_0^{G(u,u,Mu)} f(t) dt \right\} < \xi \left\{ \int_0^{G(u,u,Mu)} f(t) dt \right\}$, which is a contradiction. \therefore we get $Mu = u$

Hence $Mu = Qu = u$ i.e. u is fixed point of M and Q .

At last we prove that u is fixed point of N .

Consider, $\xi \left\{ \int_0^{G(u,u,Nu)} f(t) dt \right\} = \xi \left\{ \int_0^{G(Lu,Mu,Nu)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Pu,Qu,Ru)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Pu,Qu,Ru)} f(t) dt \right\}$

i.e. $\xi \left\{ \int_0^{G(u,u,Nu)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(u,u,Ru)} f(t) dt \right\} - \eta \left\{ \int_0^{G(u,u,Ru)} f(t) dt \right\}$

i.e. $\xi \left\{ \int_0^{G(u,u,Nu)} f(t) dt \right\} < \xi \left\{ \int_0^{G(u,u,Ru)} f(t) dt \right\}$, which means $\xi \left\{ \int_0^{G(u,u,Nu)} f(t) dt \right\} < \xi \left\{ \int_0^{G(u,u,Nu)} f(t) dt \right\}$ as $Nu = Ru$.

Which implies that $Nu = u$. Hence we get $Nu = Ru = u$.

i.e. u is fixed point of N and R .

Thus u is the common fixed point of L, M, N, P, Q and R .

Now, we prove that u is the unique common fixed point of L, M, N, P, Q and R .

If possible, let us assume that μ is another fixed point of L, M, N, P, Q and R .

$$\begin{aligned} \therefore \xi \left\{ \int_0^{G(u,u,\mu)} f(t) dt \right\} &= \xi \left\{ \int_0^{G(Lu,Mu,N\mu)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Pu,Qu,R\mu)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Pu,Qu,R\mu)} f(t) dt \right\} \\ &= \xi \left\{ \int_0^{G(u,u,\mu)} f(t) dt \right\} - \eta \left\{ \int_0^{G(u,u,\mu)} f(t) dt \right\} \end{aligned}$$

i.e. $\xi \left\{ \int_0^{G(u,u,\mu)} f(t) dt \right\} < \xi \left\{ \int_0^{G(u,u,\mu)} f(t) dt \right\}$, which is again a contradiction.

Hence finally we will have $u = \mu$.

Thus u is the unique common fixed point of L, M, N, P, Q and R .

Corollary 2.2: Let (X, G) be a complete G-metric space and $L, M, N, P: X \rightarrow X$ be mappings such that

i) $L(X) \subset P(X)$, $M(X) \subset P(X)$, $N(X) \subset P(X)$

ii) $\xi \left\{ \int_0^{G(Lx,My,Nz)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Px,Py,Pz)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px,Py,Pz)} f(t) dt \right\}$

for all $x, y, z \in X$ where $\xi: [0, \infty) \rightarrow [0, \infty)$ is a continuous and non-decreasing function,

$\eta: [0, \infty) \rightarrow [0, \infty)$ is a lower semi continuous and non-decreasing function such that

$\xi(t) = \eta(t) = 0$ if and only if $t = 0$, also $f: [0, \infty) \rightarrow [0, \infty)$ is a Lebesgue integrable function

which is summable on each compact subset of R^+ , non negative and such that for each $\epsilon > 0$,

$$\int_0^\epsilon f(t) dt > 0$$

iii) The pairs (L, P) , (M, P) , (N, P) are weakly compatible.

Then L, M, N, P have a unique common fixed point in X .

Proof : By taking $P = Q = R$ in Theorem 2.1 we get the proof.

Corollary 2.3: Let (X, G) be a complete G-metric space and $L, P: X \rightarrow X$ mappings such that

be

i) $L(X) \subset P(X)$

$$\text{ii) } \xi \left\{ \int_0^{G(Lx, Ly, Lz)} f(t) dt \right\} \leq \xi \left\{ \int_0^{G(Px, Py, Pz)} f(t) dt \right\} - \eta \left\{ \int_0^{G(Px, Py, Pz)} f(t) dt \right\}$$

for all $x, y, z \in X$ where $\xi : [0, \infty) \rightarrow [0, \infty)$ is a continuous and non-decreasing function ,

$\eta : [0, \infty) \rightarrow [0, \infty)$ is a lower semi continuous and non-decreasing function such that

$\xi(t) = \eta(t) = 0$ if and only if $t = 0$, also $f : [0, \infty) \rightarrow [0, \infty)$ is a Lebesgue integrable function

which is summable on each compact subset of R^+ , non negative and such that for each $\epsilon > 0$,

$$\int_0^\epsilon f(t) dt > 0$$

iii) The pair (L, P) is weakly compatible.

Then L, P have a unique common fixed point in X .

Proof: By substituting $L = M = N$ and $P = Q = R$ in Theorem 2.1 we get the proof.

Remark: The Corollary 2.3 is the result proved by Vishal Gupta and Naveen Mani [5] in complete metric space.

IV. References

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